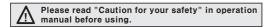
Terminal type photoelectric sensor for long distance

■Features

- •Built-in sensitivity adjuster
- ●Timer: ON Delay, OFF Delay, One-shot Delay
- •NPN/PNP open collector output (DC power type)
- •Self-diagnosis function (Green LED is lighted in stable level.)
- •Reverse power polarity and overcurrent
- ●Power supply:
 Universal 24-240VDC/24-240VAC
- •IP66 rated waterproof structure(IEC standard))







Specifications

Universal voltage type

Model Standard type With Timer		BX15M-TFR	BX5M-MFR	BX3M-PFR	BX700-DFR BX700-DFR-T					
		BX15M-TFR-T	BX5M-MFR-T	BX3M-PFR-T						
Sensing type		Transmitted beam	Retroreflective(Standard type)	Retroreflective(polarizing filter)	Diffuse reflective					
Sensing distance		15m	(*1) 0.1 ~ 5m(MS-2)	(*2) 0.1 ~ 3m(MS-3)	(*3) 700mm					
Sensing target		Opaque materials of Min. ∮15mm	Opaque material	Transparent, Translucent, Opaque material						
Hysteresis				Max. 20% at rated setting distance						
Respons	se time	Max. 20ms								
Power s	upply	24-240VAC ±10% 50/60Hz, 24-240VDC ±10% (Ripple P-P:Max. 10%)								
Current	consumption	Max. 3VA								
Light so	urce	Infrared LEI	(Modulated)	Red LED (Modulated:660nm)	Infrared LED (Modulated)					
Sensitivi	ty adjustment		Adjı	uster						
Operatio	n mode	Selectable Light ON or Dark ON by slide switch								
Control	output	Relay contact output © Contact capacity: 30VDC 3A, 250VAC 3A at resistive load, Contact composition: 1c(SPDT)								
Relay life	e cycle	Mechanically: Min. 50,000,000, Electrically: Min. 100,000								
Self-dia	agnosis output	Green LED turns on at unstable operation								
Timer fu	nction	Selectable ON Delay, OFF Delay, One Shot Delay by slide switch [Delay Time: 0.1 ~ 5sec(VR adjustable)]								
Indicato	r	Operation indicator : Yellow LED, Self-diagnosis indicator : Green LED								
Connect	tion	Terminal connection								
Insulatio	n resistance	Min. 20MΩ (at 500VDC mega)								
Insulatio	n type	Double insulation								
Noise st		$\pm 1,000 \mathrm{V}$ the square wave noise(pulse width:1 μ s) by the noise simulator								
Dielectri	c strength	1500VAC 50/60Hz for 1minute								
Impulse strength	dielectric	$1 \mathrm{kV}$ (Generator : $1.2/50 \mu\mathrm{s}$, Source impedence : 500Ω , Source energy : $0.5 \mathrm{J}$)								
Vibration	Mechanical	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours								
Vibration	['] Malfuntion	1.5mm amplitu		z in each of X, Y, Z directions	for 10 minutes					
Shock	Mechanical	500m/s ² (50G) in X, Y, Z directions for 3 times								
SHOCK	Malfuntion	100m/s ² (10G) in X, Y, Z directions for 3 times								
Ambient	illumination	Sunlight: Max. 11,000lx, Incandescent lamp: Max. 3,000lx								
Ambient	temperature	-20 ~ +65 ℃ (at non-freezing status), Storage: -25 ~ +70 ℃								
Ambient	humidity	35 ~ 85%RH, Storage : 35 ~ 85%RH								
Protection		IP66 (IEC standard)								
Material		Case: ABS, Lens: Acrylic								
Accesso	Individual	Reflector (MS-2) Reflector (MS-3)								
. 1000030	Common	Adjustment driver, Fixing bracket, Bolts/Nuts								
Approval		CE								
Unit weight		TFR: Approx. 198g, TFR-T: Approx. 203g	MFR: Approx. 126g, MFR-T: Approx. 131g	PFR: Approx. 130g, PFR-T: Approx. 134g	DFR: Approx. 110g, DFR-T: Approx. 115g					

^{※(*1)}It is same when MS-4 is used and it is able to detect under 0.1m.

K-41 Autonics

^{※(*2)}MS-2 is used, sensing distance will be 0.1~2m, it is able to detect under 0.1m.

 $[\]mbox{\ensuremath{\,\raisebox{.4ex}{\star}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\star}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\star}}}\mbox{\ensuremath{\,\raisebox{.4ex}{\bullet}$

Universal Voltage with Built-in Amplifier(Terminal type)

■ Specifications

●DC power type

Model Standard type With Timer		BX15M-TDT	BX5M-MDT	BX3M-PDT	BX700-DDT BX700-DDT-T				
		BX15M-TDT-T	BX5M-MDT-T	BX3M-PDT-T					
Sensin	g type	Transmitted beam	Retroreflective (Standard type)	Retroreflective (Polarizing filter)	Diffuse reflective				
Sensin	g distance	15m	(*1) 0.1 ~ 5m (MS-2)	(*2) 0.1 ~ 3m(MS-3)	(* 3) 700mm				
Sensin	g target	Opaque materials of Min. ø15mm	Opaque materials of Min. Ø60mm	Opaque materials of Min. Ø60mm	Transparent, Translucent, Opaque material				
Hystere	esis				Max. 20% at rated setting distance				
Respor	nse time		Max.	1ms	I.				
Power	supply		12-24VDC ±10% (R	ipple P-P:Max. 10%)					
Curren	t consumption	Max. 40mA		Max. 30mA					
Light s	ource	Infrared LEI	O(Modulated)	Infrared LED (Modulated)	Infrared LED (Modulated)				
Sensitiv	vity adjustment	Adjuster							
Operat	ion mode	Selectable Light ON or Dark ON by slide switch							
Control output		 NPN open collector output Load voltage: Max. 30VDC, Load current: Max. 200mA,							
Self-di	iagnosis output	NPN open collector output F Load voltage : Max. 30VDC, Load current : Max. 50mA, Residual voltage : Max. 1V at 50mA, Max. 0.4V at 16mA							
Protection circuit		Reverse polarity protection, Overload & short circuit pretection							
Timer function		Selectable ON Delay, OFF Delay, One Shot Delay by slide switch [Delay Time: 0.1 ~ 5sec(VR adjustable)]							
Indicat	tor	Operation	on indicator : Yellow LED, S	elf-diagnosis indicator : Gr	een LED				
Conne	ction	Terminal connection							
Insulat	ion resistance	Min. 20MΩ (at 500VDC mega)							
Noise s	strength	$\pm 240 \mathrm{V}$ the square wave noise (pulse width: 1 μ s) by the noise simulator							
Dielect	ric strength		1000VAC 50/6	OHz for 1minute					
Vibratio	on	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours							
Shock		500m/s² (50G) in X, Y, Z directions for 3 times							
Ambier	nt illumination	Sunlight: Max. 11,000lx, Incandescent lamp: Max. 3,000lx							
Ambier	nt temperature	-20 ~ +65 ℃ (at non-freezing status), Storage : -25 ~ +70 ℃							
Ambient humidity		35 ~ 85%RH, Storage : 35 ~ 85%RH							
Protection		IP66(IEC standard)							
Material		Case: ABS, Lens cover: Acrylic, Lens: Acryl							
Access	Individual		Reflector (MS-2) Reflector (MS-3)						
	Common	Adjustment driver, Fixing bracket, Bolts/Nuts							
Approv	/al	C€							
	eight	Approx. 212g	Approx. 124g	Approx. 142g	Approx. 117g				

 $[\]ensuremath{\,\%\,}\xspace(\star\,\mathbf{1})$ It is same when MS-4 is used and it is able to detect under 0.1m.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

> (G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

Autonics K-42

^{※(*2)}MS-2 is used, sensing distance will be 0.1~2m, it is able to detect under 0.1m.

^{*(*3)}It is for Non-glossy white paper(200 \times 200mm).

BX Series

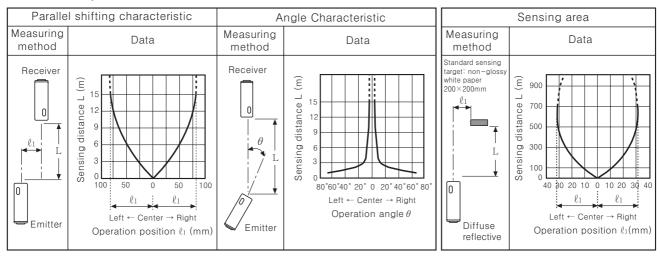
■ Feature data

OTransmitted beam

- ●BX15M-TFR / BX15M-TFR-T
- ●BX15M-TDT / BX15M-TDT-T

ODiffuse reflective

- ●BX700-DFR / BX700-DFR-T
- ●BX700-DDT / BX700-DDT-T



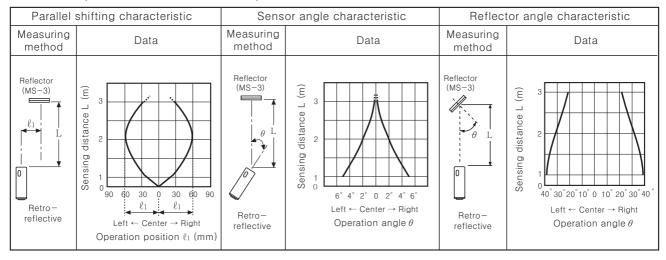
ORetroreflective

●BX5M-MFR / BX5M-MFR-T ●BX5M-MDT / BX5M-MDT-T

Paralle	l shifting characteristic	Sens	or angle characteristic	Reflector angle characteristic			
Measuring method	Measuring Data		Data	Measuring method	Data		
Reflector (MS-2) \$\begin{align*} \lambda_1 & \ldots & \l	(E) $\frac{1}{1}$ Operation position ℓ_1 (mm)	Reflector (MS-2) ### A L Retro- reflective	(E) 5 1 9 0 4 4 2 1 9 1 9 1 9 1 9 1 9 1 9 1 9 1 9 1 9 1	Reflector (MS-2) ### A L O	$(\widetilde{\mathbb{E}}) \ \ 5$ 0 0 0 0 0 0 0 0 0 0		

OPolarized retroreflective

●BX3M-PFR / BX3M-PFR-T ●BX3M-PDT / BX3M-PDT-T

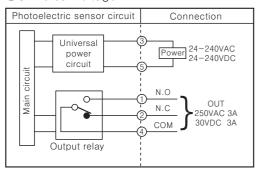


K-43 Autonics

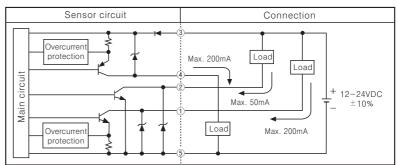
Universal Voltage with Built-in Amplifier(Terminal type)

■Control output diagram

OUniversal voltage



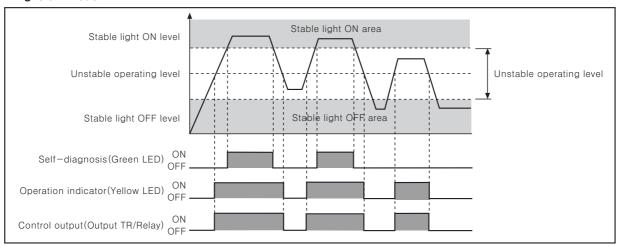
ODC voltage



^{*}In case of product with the output protection device, if terminals of control output are short—circuited or overcurrent condition is existed, the control output will turn off due to protection circuit.

Operation mode and timing diagram

●Light ON mode



^{*}Operation for Dark ON mode is opposed to above chart indication for Light ON mode.

■ Timer mode

Timer mode	Switch position		Status of light		ON		1 [
rimer mode	S1	S2	Operation mode		OFF	-	 	-	
NORMAL MODE	ON	ON	Light ON		ON OFF				
NORMAL MODE			Dark ON	OUT (Control output)	ON OFF				
ONE SHOT DELAY	ON	OFF	Light ON	OUT (Control output)	ON OFF	T		T	T
MODE			Dark ON	OUT (Control output)	ON OFF	-	T	T	
	OFF	F ON	Light ON	OUT (Control output)	ON OFF	T			1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ON DELAY MODE			Dark ON	OUT (Control output)	ON OFF		T	T	
OFF DELAY MODE	OFF OFF	٥	Light ON	OUT (Control output)	ON OFF		T	T	T
OFF DELAY MODE		OFF	Dark ON	OUT (Control output)	ON OFF	T			

★T: Time set by timer adjuster.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

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(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

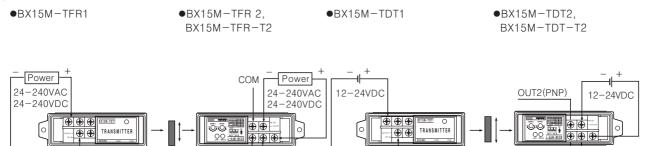
Autonics K-44

^{*}To prevent from the misoperation, output of units keeps the state of OFF for 0.5sec. after power ON.

BX Series

Connections

Transmitted beam



©Retroreflective / Retroreflective with polarizing filter

Sensing

target

N·O

N·C

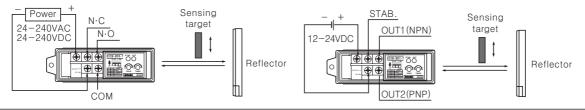
- ●BX5M-MFR, BX5M-MFR-T
- ●BX3M−PFR, BX3M−PFR−T
- ●BX5M-MDT, BX5M-MDT-T

Sensina

target

OUT1(NPN)

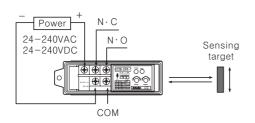
●BX3M-PDT, BX3M-PDT-T

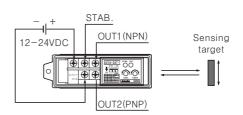


ODiffuse reflective

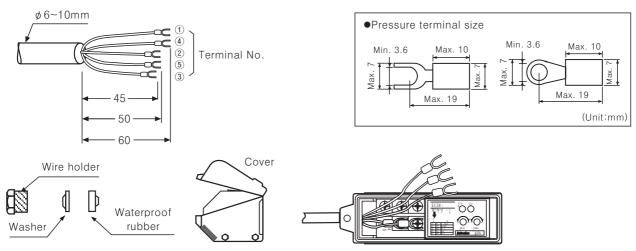
●BX700-DFR, BX700-DFR-T

●BX700-DDT, BX700-DDT-T





Cable



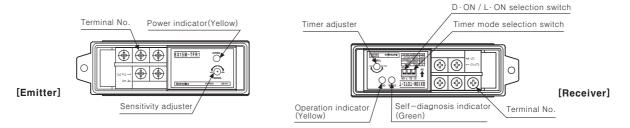
- *On servicing wire, connect wire on terminal as above figure.
- *Select the round wire with the size of ϕ 6 ~10mm for the waterproof and tighten the cable holder by torque of 1.0 to 1.5N m.
- **On servicing wire, tighten screw of terminals by torque of 0.8N m.
- $\mbox{\em MOn}$ mounting the cover, tighten the cover nut by torque of 0.3~0.5N $\mbox{\em o}$ m.

K-45 Autonics

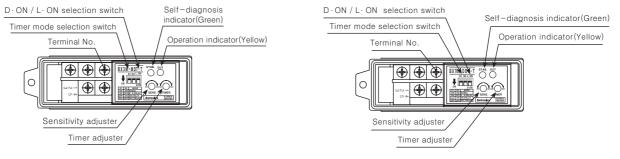
Universal Voltage with Built-in Amplifier(Terminal type)

■ Front panel identification

©Transmitted beam

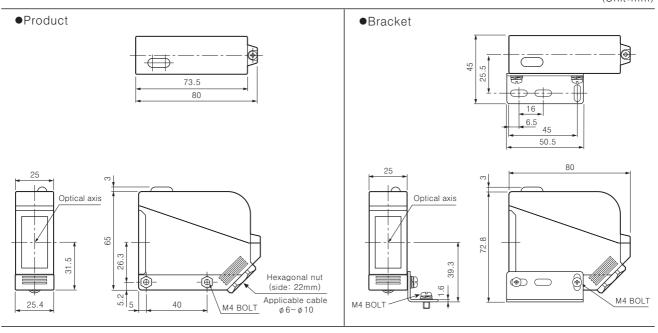


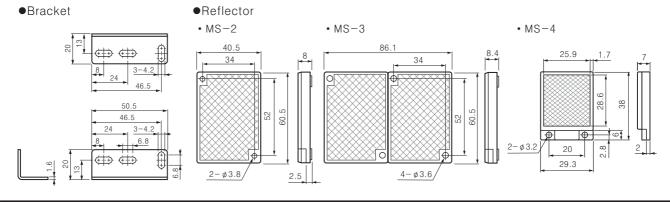
©Retroreflective / Retroreflective with polarizing filter ©Diffuse reflective



*There are no Timer mode selection switch and Timer adjuster in type without Timer function.

■ **Dimensions** (Unit:mm)





(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel

(F)

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

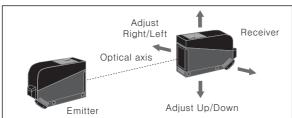
(P) Production stoppage models & replacement

Autonics K-46

Mounting and sensitivity adjustment

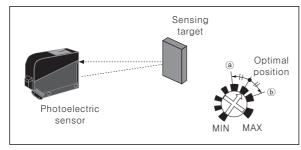
OTransmitted beam type

- 1. Supply the power to the photoelectric sensor, after set the emitter and the receiver facing each other.
- 2. Set the receiver in center of position in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If the sensing target is translucent body or smaller than \$\phi 15mm\$, it can be missed by sensor cause light penetrate it.
- **Sensitivity adjustment : Please see the diffuse reflective type.



ODiffuse reflective type

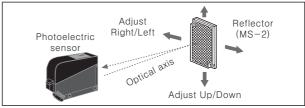
- 1. The sensitivity should be adjusted depending on a sensing target or mountin place.
- 2. Set the target at a position and turn sensitivity adjuster from minimum sensitivity position slowly, confirm position (a) in the middle of the operation range of indicator and self diagnosis indicator (Green LED) is OFF.
- 3. If turn adjuster higher slowly in state of removed target, the operation indicator (Yellow LED) will be OFF and self diagnosis indicator (Green LEd) will be ON. Confirm this position as (a).
 - [When self diagnosis indicator (Green LED) and operation indicator (Yellow LED) are OFF, the Max. sensitivity position will be (b).]
- 4. Set the adjuster at the center of two switching position (a), (b).
- **Above sensitivity adjustment is when it is the state of Light ON mode. If it is the state of Dark ON mode, operation indicator(Yellow LED) will be opposite.



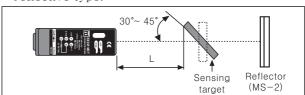
*The sensing distance indicated on specification chart is against 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.

©Retroreflective type

- 1. Supply the power to the photoelectric sensor, after set the photoelectric sensor and the reflector(MS-2) facing each other.
- 2. Set the photoelectric sensor in the middle of the operation range of indicator adjusting the reflector or the sensor right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.



- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- **If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photo sensor. Therefore put enough space between the target and photoelectric sensor or the surface of target should be installed at an angle of 30° ~ 45° against optical axis. (When detecting target with high reflectance near by, photoelectric sensor with the polarizing filter should be used.)
- *Sensitivity adjustment : Please refer to the diffuse reflective type.

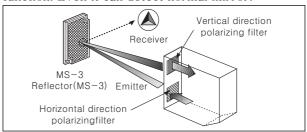


*If the mounting place is too small, please use MS-4 instead of MS-2 for same sensing distance.



©Retroreflective type(With polarizing filter)

The light passed through the polarizing filter of emitter reaches to MS-3 converting as horizontal direction, it reaches to photodetector through the filter of receiver converting as vertical by MS-3 function. Even it can detect normal mirror.



K-47 Autonics